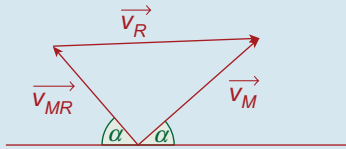


Q. 24.



$$\vec{v}_{MR} = -5 \cos \alpha \vec{i} + 5 \sin \alpha \vec{j}$$

$$\vec{v}_R = 13 \vec{i}$$

$$\vec{v}_M = (13 - 5 \cos \alpha) \vec{i} + 5 \sin \alpha \vec{j}$$

$$\tan \theta = \frac{j\text{-component}}{i\text{-component}} = \frac{5 \sin \alpha}{13 - 5 \cos \alpha}$$

$$\frac{d(\tan \theta)}{d\alpha} = \frac{(13 - 5 \cos \alpha)(5 \cos \alpha) - 5 \sin \alpha (5 \sin \alpha)}{(13 - 5 \cos \alpha)^2} = 0$$

$$\Rightarrow 65 \cos \alpha - 25 \cos^2 \alpha - 25 \sin^2 \alpha = 0$$

$$\Rightarrow 65 \cos \alpha - 25(\cos^2 \alpha + \sin^2 \alpha) = 0$$

$$\Rightarrow 65 \cos \alpha - 25 = 0$$

$$\Rightarrow \cos \alpha = \frac{5}{13}$$

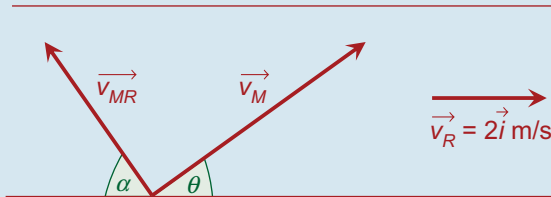
The shortest path is where  $\theta$  is a maximum and therefore where  $\tan \theta$  is a maximum, since  $\tan \theta$  is an increasing function in  $\theta$ . That is to say that the shortest path is where  $\cos \alpha = \frac{5}{13}$ ,

and hence  $\sin \alpha = \frac{12}{13}$

$$\begin{aligned} \text{In this case } \vec{v}_M &= \left(13 - 5\left(\frac{5}{13}\right)\right) \vec{i} + 5\left(\frac{12}{13}\right) \vec{j} \\ &= \frac{144}{13} \vec{i} + \frac{60}{13} \vec{j} \end{aligned}$$

$$\text{Crossing time} = \frac{60}{\frac{60}{13}} = 13 \text{ s}$$

Q. 25.



$$\vec{v}_{MR} = -\cos \alpha \vec{i} + \sin \alpha \vec{j}$$

$$\vec{v}_R = 2 \vec{i}$$

$$\vec{v}_{MR} = \vec{v}_M - \vec{v}_R$$

$$\Rightarrow \vec{v}_M = \vec{v}_{MR} + \vec{v}_R$$

$$= (2 - \cos \alpha) \vec{i} + \sin \alpha \vec{j}$$

$$\Rightarrow \tan \theta = \frac{\sin \alpha}{2 - \cos \alpha}$$

$\tan \theta$  will have a maximum value when  $\frac{d}{d\alpha}(\tan \theta) = 0$

$$\frac{d}{d\alpha}(\tan \theta) = \frac{(2 - \cos \alpha)(\cos \alpha) - (\sin \alpha)(\sin \alpha)}{(2 - \cos \alpha)^2} \quad \dots \text{ using the Quotient Rule}$$